

Recovering Real-world Reflectance Properties and Shading from HDR Imagery

Bjoern
Haefner^{1,2}

Simon
Green¹

Alan
Oursland¹

Daniel
Andersen¹

Michael
Goesele¹

Daniel
Cremers²

Richard
Newcombe¹

Thomas
Whelan¹

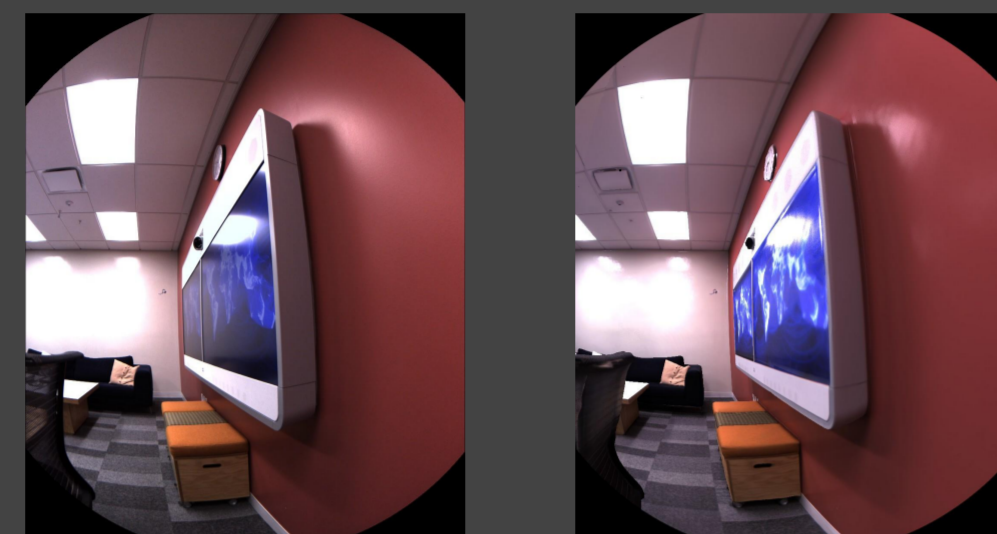


¹ Reality Labs Research (Meta) ² Technical University of Munich



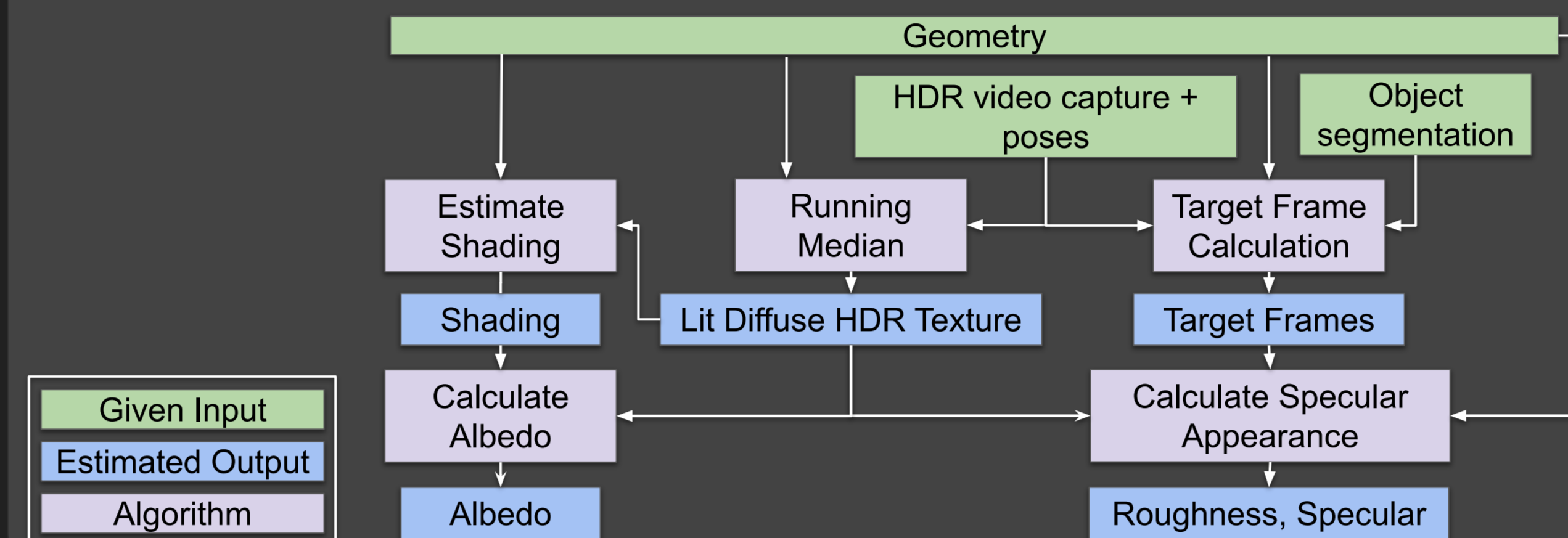
Introduction

- Estimate material parameters for each object in large scale scenes
- Enables faithful reconstructions
- Plausible scene relighting
- Visually accurate rendering of virtual objects



Camera Capture Proposed

Algorithm



Specular Appearance Estimation

$$I^i(p) = I_d^i(p) + I_{nd}^i(p; \varphi^i, \psi^i)$$

- $I^i(p)$: i -th objects target frame
- $I_d^i(p)$: Diffuse part (rendered using L_d)
- $I_{nd}^i(p; \varphi^i, \psi^i)$: Non-diffuse part

$$\min_{\varphi^i, \psi^i \in [0,1]} \sum_{p \in \Omega^i} \|I^i(p) - (I_d^i(p) + I_{nd}^i(p; \varphi^i, \psi^i))\|^2, \quad \forall i$$

⇒ Grid search in φ^i , with nested least squares optimization in ψ^i

Rendering Equation and BRDF Model

Rendering equation:

$$I(p) = L_o(x, \omega_o) = \int_{\mathcal{H}^2} f_r(x, \omega, \omega_o) L(x, \omega) \langle \omega, n \rangle d\omega$$

Split BRDF into diffuse (albedo) and non-diffuse (specular appearance) part:

$$f_r(x, \omega, \omega_o) = f_d(x) + f_{nd}(x, \omega, \omega_o)$$

$$f_d(x; \rho) = \rho(x) \quad (\text{Diffuse/Albedo})$$

$$f_{nd}(x, \omega, \omega_o; \varphi, \psi) = G(\varphi)D(\varphi)F(\psi) \quad (\text{Non-Diffuse})$$

Plug into rendering equation:

$$L_o(x, \omega_o) = L_d(x) + L_{nd}(x, \omega_o)$$

$$L_d(x) := \rho(x) \int_{\mathcal{H}^2} L(x, \omega) \langle \omega, n \rangle d\omega$$

$$L_{nd}(x, \omega_o) := \int_{\mathcal{H}^2} f_{nd}(x, \omega, \omega_o; \varphi, \psi) L(x, \omega) \langle \omega, n \rangle d\omega$$

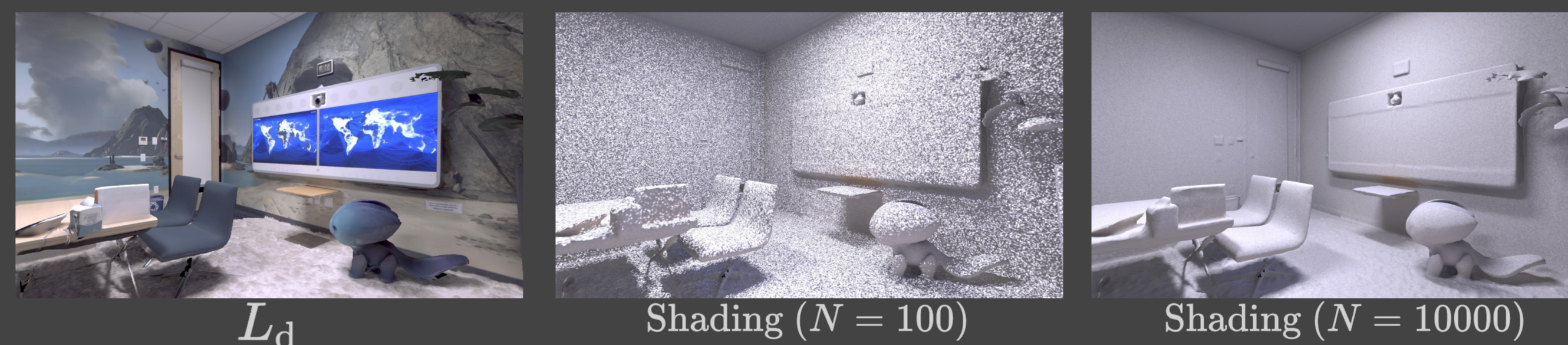
Albedo and Shading Estimation

- First estimate shading, then solve for albedo in closed form:

$$\underbrace{L_d(x)}_{\text{Median Texture}} = \underbrace{S(x)}_{\text{Shading}} \cdot \underbrace{\rho(x)}_{\text{Albedo}} \implies \rho(x) = \frac{L_d(x)}{S(x)}$$

$$S(x) = \int_{\mathcal{H}^2} L(x, \omega) \langle \omega, n \rangle d\omega \approx \sum_{i=1}^N L(x, \omega_i) \langle \omega_i, n \rangle$$

- Cast N rays $(x, \omega_i), i = 1, \dots, N$, at each point $x \in \mathbb{R}^3$ in direction $\omega_i \in \mathcal{H}^2$
- At each rays hitpoint $\tilde{x}_i \in \mathbb{R}^3$: $L(x, \omega_i) = L_d(\tilde{x}_i)$



L_d Shading ($N = 100$) Shading ($N = 10000$)

Target Frame Calculation

Use *only 1* target frame for each object:

- Less computational complexity
- Fast

Target frame should fulfill:

- \mathcal{A}_1 : High chance of specular highlight caused by direct illumination
- \mathcal{A}_2 : HDR capture consists of valid pixels, i.e. not over-/under-saturated

	Rendered Specularity			
	Observation			
\mathcal{A}_1		✓	✗	✓
\mathcal{A}_2		✗	✓	✓

Lit Diffuse HDR Texture

- Running mean on HDR 16-bit data has artifacts
- Use running median instead of mean
- Assume median texture equals diffuse radiance L_d

⇒ Median texture = L_d = Lit diffuse HDR texture



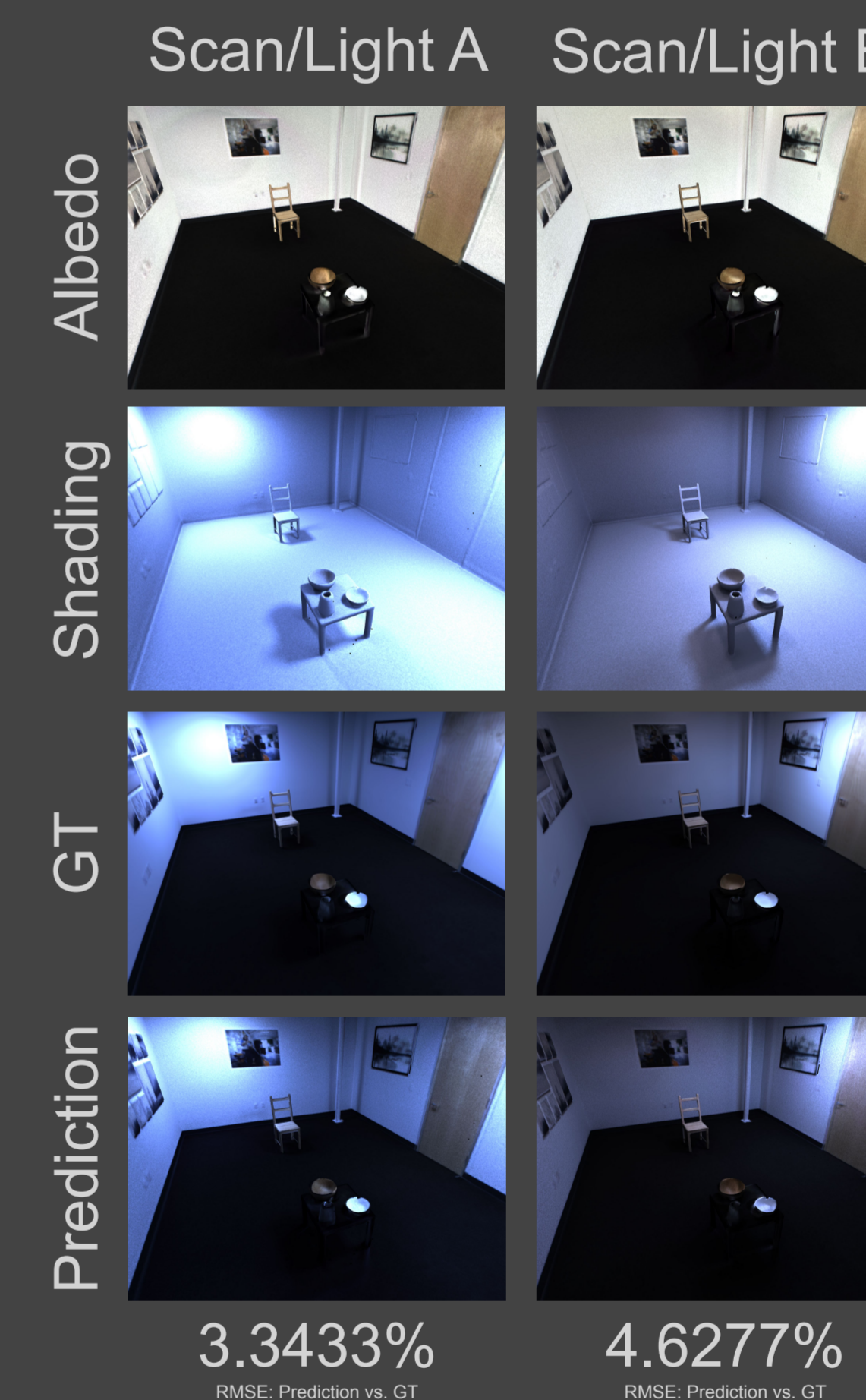
Running Mean



Running Median

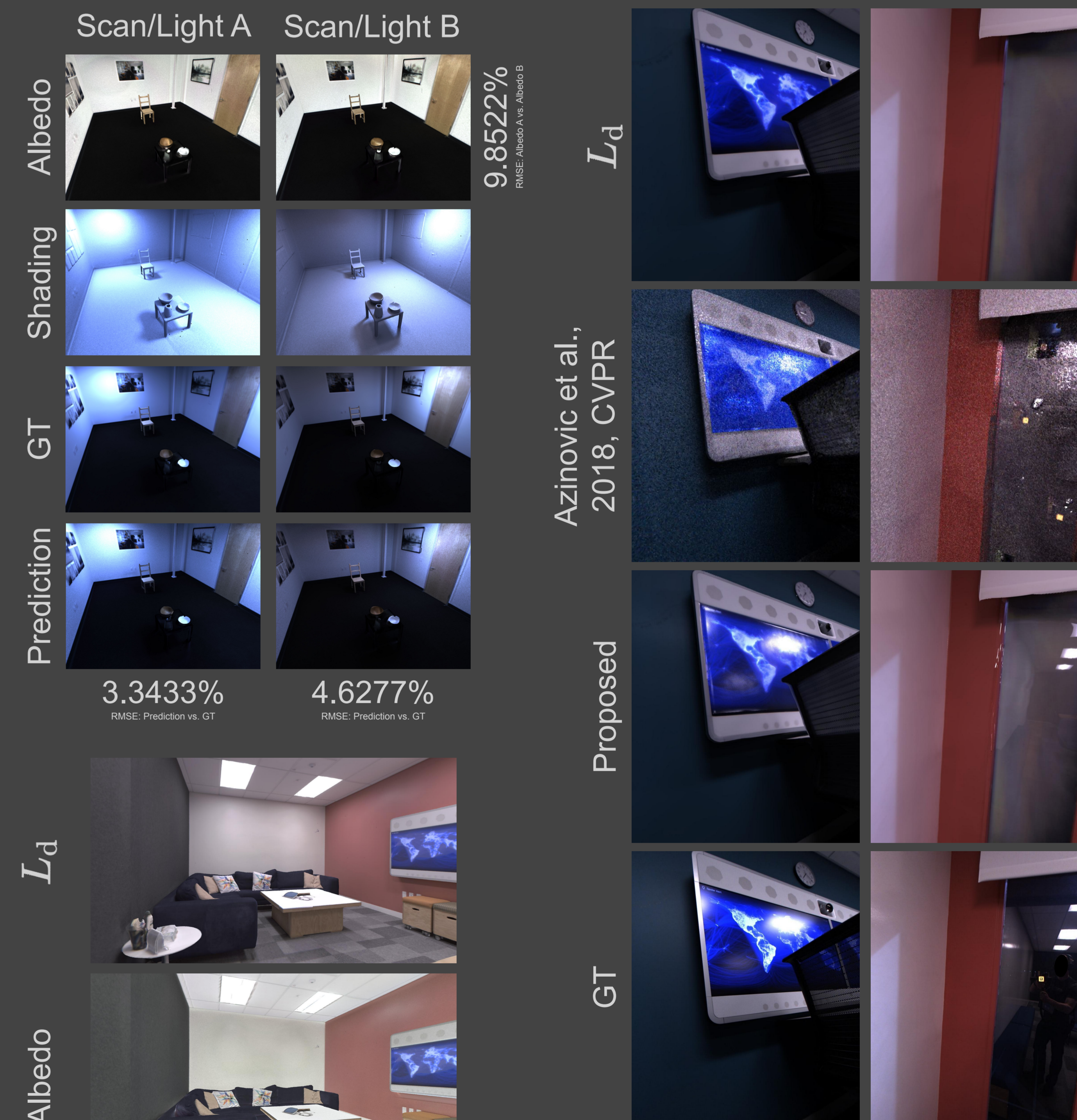
Evaluation

Albedo/Shading



3.3433% RMSE: Prediction vs. GT 4.6277% RMSE: Prediction vs. GT

Specular Appearance



9.8522% RMSE: Albedo vs. Albedo B

Azinovic et al., 2018, CVPR

Proposed

GT

Relighting

